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# Comparing Some Adjacency Matrices to Estimate a Spatial Negative Binomial Regression Model

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*Abstract*—The spatial regression model is used to illustrate the extent of the influence of independent variables on the dependent variable with the presence of spatial effects of adjacent locations. In such models, the dependent variable usually follows the normal distribution. In this research, a different case was studied, which is when the dependent variable is distributed in a negative binomial distribution, which is considered one of the important discrete distributions, and the basis of statistical models for count data. This distribution is suitable for data with overdispersion characteristics. In this research, a spatial negative binomial regression model is estimated using the maximum likelihood method of estimation, and based on the Queen adjacency criteria and the proposed longitudes to form the modified weight matrix, and simulation study is conducted to choose the best matrix from among the two used matrices. The results showed that the modified proposed longitude matrix is the best, as it was used to estimate the parameters of the negative binomial regression model using traffic accident data for 14 Iraqi governorates for the year 2022 as a response variable and based on the explanatory variables (temperature, rainfall, and amount of falling dust). The results showed that there is an effect of temperature and rainfall on the number of traffic accidents with spatial dependence.

Keywords—Binary adjacency matrix; proposed longitude criterion; spatial negative binomial regression model.

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## I. INTRODUCTION

Over the course of the last thirty to forty years, spatial models have been utilized in a broad variety of econometric applications. The modeling of spatial heterogeneity is the application that is utilized the most frequently in relation to the examination of census facts. In the first attempt to define spatial econometrics and its methodology, authors in [1] released a tiny volume with the title Spatial Econometrics. This volume was recognized as the first attempt. A number of publications on spatial analysis and spatial time series were published in the same year after they were first published. Inquiries and studies by [2], [3] include information that is associated with locations, spatial data is considered to be spatially oriented data. This data is distinct from other data in that it has two essential components, namely information denoting the place (spatial) and information that describes the attributes of the location. The geographic coordinates, such as latitude and longitude, are the subject of the information pertaining to location [4].

In contrast, descriptive information, often known as nonspatial information, includes facts like the density of the material and the sort of metal it is. There are distinctions in the circumstances of each of the places [5]. There is, however, a tight association between the state of each site and the condition of surrounding sites, and the correlation between the sites that were analyzed is referred to as spatial heterogeneity [6]. Among the several types of regression, one that is dependent on spatial variables is called spatial regression. When it comes to regression models. The link between the variables that are being explained and those that are being explained can be referred to as spatial dependency. Every piece of information that the researcher analyzes for any phenomena that he is interested in studying is not autonomous in and of itself; rather, it is reliant on the source of the information [7]. Studies in [8] and [9] aims to estimate a spatial negative binomial regression model (SAR), Using the maximum likelihood method, relying on the Quinn adjacency criterion, and a new adjacency criterion, relying on longitudes, and comparing them using the simulation method to reach the most appropriate matrix in obtaining an efficient estimate of the model, and then using it in the applied aspect in estimating the number of traffic accidents in the Iraqi governorates .

## A. The spatial negative binomial regression model

An investigation of a spatial regression model is carried out with the purpose of elucidating the amount to which the independent variables have an impact on the dependent variable, taking into account the geographical impacts of neighboring sites. Researchers in the field of measurement have produced a number of spatial models that are concerned with spatial analysis processes, applying them to a wide variety of applications, and dealing with spatial dependency [10].

$$\mu^{SAR} = exp((I - \lambda w)^{-1} x\beta)$$
(1)

w is the spatial adjacency matrix with dimension  $(n \times n)$ .

 $\lambda$  is the spatial correlation parameter.

x is the matrix of variables.

 $\beta$  is a vector of parameters.

#### B. Binary contiguity matrix

Providing data allows the construction of a spatial weight matrix based on proximity. We assume that n refers to the number of spatial units. The spatial weight matrix with dimension  $n \times n$  will be denoted by the symbol W, and it will be a positive, square, symmetric and non-random matrix. Each element within the matrix is denoted by W<sub>ij</sub> at location i,j. A value is assigned to each pair at adjacent or non-adjacent locations by some predefined rules that define the spatial relationship between the locations. The general formula for the spatial weight matrix is as follows [11], [12].

$$W_{ij} = \{1 \quad if \quad i \text{ neighbour } j$$
 (2)

Through formula (2), the values of each element of the spatial weights' matrix are determined. Where if the sites i and j are adjacent, then the value of  $W_{ij}=1$ , and if they are not adjacent, then the value of  $W_{ij}=0$ . The elements of the main diagonal of the weight matrix are equal to zero because the regions are not adjacent to themselves [13], [14], [15].

## C. Adjusted Weight Matrix

This matrix is based on the binary adjacency weights matrix W\_ij after modifications have been made to it, in which the sum of the row equals one, as in the following formula [16], [17].

$$W_{ij \ adj} = \{ \frac{\frac{W_{ij}}{\Sigma W_{ij}} \ i \ neighbor \ j}{0 \ other \ wise} \ 1$$
(3)

There are several types of adjacencies to build the weight matrix, we will take the following:

1) Modified Queen Criterion (M-Q-C): This juxtaposition occurs by merging the Rook and Bishop matrix, i.e. the subscription becomes boundaries and points of the region. If the region shares a border or point, then the value of  $W_Q = 1$ , and if the region does not have a border or point with the neighboring region, then the value of  $W_Q = 0$ .

2) Contiguity criterion for proposed modified longitudes (C-C-P-M-L): This Contiguity is between two or more neighboring regions through which a common longitude passes, where the value of the region through which the longitude passes has a value of  $W_{ij}=1$ , and the common region

through which the longitude does not pass has a value of  $W_{ij}=0$ .

# D. The Maximum Likelihood Method for Estimating a Spatial Negative Binomial Regression Model

Maximum likelihood estimators are stable, highly efficient, and consistent. That is, the estimation process is done by making the estimates of the maximum likelihood function for the random variables as large as possible [18], [19].

$$f(y_i \mid \mu_i, \theta) = \frac{\Gamma(y_i + \theta^{-1})}{\Gamma(y_i + 1)\Gamma(\theta^{-1})} \left(\frac{\theta^{-1}}{\mu_i^{SAR} + \theta^{-1}}\right)^{\alpha^{-1}} \left(\frac{\mu_i^{SAR}}{\mu_i^{SAR} + \theta^{-1}}\right)^{y_i}$$
(4)

Where  $\theta \ge 0$ , i = 1, 2, ..., n

( )

$$ln \ L(\theta, \beta) = \sum_{i=1}^{n} \left\{ \left( \sum_{j=0}^{y-1} ln \left( j + \theta^{-1} \right) \right) - ln \left( y_{i} \right) - \left( y_{i} + \theta^{-1} \right) ln \left( 1 + \theta \mu_{i}^{SAR} \right) + y_{i} \right\}$$

$$ln \ \theta + y_{i} \ ln \ \mu_{i}^{SAR}$$

Since

$$\mu_i^{SAR} = exp \left[ (I - \lambda w)^{-1} x \beta \right]$$

To obtain the maximum likelihood estimates for a spatial negative binomial regression model. Numerical estimation methods can be adopted, such as tRaphson method. Therefore, we must find the first and second derivatives of the model parameters [20], [21].

$$\frac{\partial \ln L}{\partial \lambda} = \sum_{i=1}^{n} \left\{ -(y_i) + \theta^{-1} \frac{\beta x w \exp((I - \lambda w)^{-1} x \beta)}{\theta (I - \lambda w)^2 \left(\frac{\exp((I - \lambda w)^{-1} x \beta)}{\theta} + 1\right)} + \frac{\beta x w y}{(I - \lambda w)^2} \right\} = 0$$
(6)

Derivation with the ratio  $(\beta, \theta)$  produces the following equations: [18].

$$\frac{\partial \ln L}{\partial \beta} = \sum_{i=1}^{n} x_i \frac{(y_i - \mu_i^{SAR})}{1 + \theta \mu_i^{SAR}} = 0$$
(7)

$$\frac{\partial \ln L}{\partial \theta} = \sum_{i=1}^{n} \left[ \frac{1}{\alpha^2} \left( \ln(1 + \theta \,\mu_i^{SAR}) + \frac{\theta(y_i - \mu_i^{SAR})}{1 + \theta \,\mu_i^{SAR}} \right) + \psi\left(y_i + \frac{1}{\theta}\right) - \psi\left(\frac{1}{\theta}\right) \right] = 0$$
(8)

## E. Moran's coefficient test

It is a tool for measuring spatial dependence in the studied data, it is symbolized by the symbol I and is analogous to the Durbin Watson test in time series data. Its value ranges between (1+, 1-), as the closer the value of the Moran's coefficient is to (1+), the spread pattern of the data is close. However, if the value of the Moran's coefficient approaches (1-), the spread pattern of the data is divergent, but if the value approaches (0).) The spread of data is random. The formula for Moran's coefficient is [22], [23], [24].

$$I = \frac{n}{S_0} \frac{\sum_{i=1}^{n} \sum_{j=1}^{n} w_{ij} (y_i - \underline{y}) (y_j - \underline{y})}{\sum_{i=1}^{n} (y_i - \underline{y})^2}$$
(9)  
$$S_0 = \sum_{i=1}^{n} \sum_{j=1}^{n} W_{ij}$$

whereas:

S The sum of the elements in the matrix W.

n sample size.

W is a matrix of adjacency weights with dimensions n×n.

#### F. Mean Squares Error

It is calculated for the model for all matrices used. This criterion is one of the important comparison criteria in regression models. There is an inverse relationship between the MSE and the significance of the model, where the lower the MSE, the greater the significance of the model and vice versa. The formula for this standard [25], [26] is as follows:

$$MSE = \frac{1}{p} \sum_{i=1}^{p} \left(\widehat{B}_i - B\right)^2 \tag{10}$$

whereas:

p: represents the number of times the experiment was repeated (B\_i) represents the estimated value of parameter i B represents the real parameter value

# II. MATERIALS AND METHOD

#### A. Stages of the simulation experiment

The R 4.3.0 programming language was used to write the simulation program, which is attached in Appendix A. The written program includes four basic stages for estimating a negative binomial regression mod. At this stage, the default values for the parameters are chosen considering the presence of three explanatory variables [27][28][29]. Different default values were chosen for the parameters and these values are shown in Table 1.

	TABLE	I	
DEFAULT VAL	UES FOR	PARAM	METERS

Model	β <sub>0</sub>	β <sub>1</sub>	β <sub>2</sub>	$\beta_3$	θ	λ
1	0.1	0.1	0.1	0.1	1/2	0.2
2	2	0.07	-0.02	0.2	1/2	0.2
3	0.5	0.3	0.2	0.4	1/2	0.2
4	0.1	0.1	0.1	0.1	1/8	0.2
5	2	0.07	-0.02	0.2	1/8	0.2
6	0.5	0.3	0.2	0.4	1/8	0.2
7	0.1	0.1	0.1	0.1	1/2	0.8
8	2	0.07	-0.02	0.2	1/2	0.8
9	0.5	0.3	0.2	0.4	1/2	0.8
10	0.1	0.1	0.1	0.1	1/8	0.8
11	2	0.07	-0.02	0.2	1/8	0.8
12	0.5	0.3	0.2	0.4	1/8	0.8

#### B. Generating data

At this stage, the explanatory variables are generated as being generated from a uniform distribution [30]. The error is generated from a negative binomial distribution, and then the dependent variable is collected according to the approved model. Each experiment was repeated 5000 times. Three different sample sizes were chosen (56, 112, 168).

## III. RESULTS AND DISCUSSION

## A. Contiguity criterion for proposed modified longitudes (C-C-P-M-L) Modified Queen Criterion (M-Q-C)

The MSE criteria was utilized for the aim of evaluating several weight matrices for parameters and locating the optimal weight matrix. This is because the matrix that has the lowest MSE value is deemed to be superior. As shown in Tables 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12 and 13.

TABLE II	
ESTIMATION VALUES OF PARAMETERS AND MSE OF MATRICES FOR THE FIRST CASE	E

n	Matrix	β0	β1	β2	β3	θ	λ	MSE	
56	C-C-P-M-L	0.09669	0.09961	0.09954	0.10011	0.46839	0.20474	0.14247	
	M-Q-C	0.06654	0.10047	0.10040	0.09980	0.46854	0.20644	0.14342	
112	C-C-P-M-L	0.10745	0.09951	0.09976	0.09969	0.48586	0.20004	0.06598	
	M-Q-C	0.06932	0.10060	0.09989	0.10052	0.48249	0.20002	0.06793	
168	C-C-P-M-L	0.13152	0.09841	0.10012	0.10023	0.48943	0.19992	0.03846	
	M-Q-C	0.08893	0.10008	0.10026	0.09992	0.48983	0.19987	0.04290	
				TABLE III					
		ESTIMATION VA	LUES OF PARAME	TERS AND MSE OF	MATRICES FOR TH	HE SECOND CASE			
n	Matrix	β0	β1	β2	β3	θ	λ	MSE	
56	C-C-P-M-L	1.92344	0.07168	-0.01903	0.20049	0.46678	0.20280	0.13347	
	M-Q-C	1.98511	0.06968	-0.01958	0.19985	0.46631	0.19877	0.14436	
112	C-C-P-M-L	1.96347	0.07134	-0.02041	0.19970	0.48607	0.19989	0.06361	
	M-Q-C	2.02933	0.06862	-0.02025	0.20004	0.48564	0.19922	0.06393	
168	C-C-P-M-L	2.02786	0.06871	-0.01988	0.19993	0.49027	0.20052	0.04235	
	M-Q-C	1.99045	0.07005	-0.01985	0.20007	0.48930	0.20010	0.04031	

		ESTIMATION VALU	JES OF PAR	TABLE	IV /ISE of mate	RICES FO	)R THE THIRD	CASE		
n	Matrix	β0		β1	β2	ĺ	3	θ	λ	MSE
56	C-C-P-M-L	0.48286	<b>6</b> 0	.30021 (	).19963	0.3	9964	0.47002	0.20211	0.13128
110	M-Q-C	0.51903	3 O	.29909 (	0.20016	0.3	9878	0.46518	0.20301	0.14935
112	C-C-P-M-L	0.51/21	. 0	.29854 (	0.20058	0.40	0021	0.48490	0.20007	0.06304
169	M-Q-C C C P M I	0.4/991		.30036 (	0.20020	0.3	9972 0032	0.48316	0.20015	0.065/6
100	MOC	0.50320	) () ) ()	.29944 (	) 10083	0.40	0032	0.48700	0.20012	0.03999
	M-Q-C	0.50500	) 0	.29963 (	.19965	0.5	7940	0.49129	0.20080	0.04237
		ESTIMATION VALUE	ES OF PARA	TABLE AMETERS AND M	V SE of matri	ICES FO	R THE FOURT	H CASE		
n	Matrix	β0		β1	β2		β3	θ	λ	MSE
56	C-C-P-M-L	0.0951	7	0.10008	0.10007	0.0	9972	0.11493	0.20102	0.03508
	M-Q-C	0.1180	15	0.09908	0.09979	0.1	0012	0.11441	0.19945	0.03841
112	C-C-P-M-L	0.1084	-2	0.09953	0.09982	0.1	0038	0.12059	0.19901	0.01724
1.0	M-Q-C	0.0940	16 12	0.10015	0.10000	0.0	9994	0.12104	0.19827	0.01983
108	C-C-P-M-L M O C	0.0975	2	0.10003	0.10024	0.0	0002	0.12086	0.20053	0.01106
	M-Q-C	0.0902	.5	0.10010	0.10008	0.1	0002	0.12222	0.20023	0.01255
		ESTIMATION VALU	JES OF PAR	I ABLE AMETERS AND N	VI MSE OF MATI	RICES F	OR THE FIFTH	CASE		
n	Matrix	β0		β1	β2		β3	θ	λ	MSE
56	C-C-P-M-L	2.005	96	0.06955	-0.02007		0.20009	0.11589	0.19783	0.03411
	M-Q-C	1.992	48	0.07015	-0.02007		0.19991	0.11789	0.19750	0.03539
112	C-C-P-M-L	1.986	32	0.07043	-0.02021		0.20016	0.12041	0.19962	0.01657
	M-Q-C	2.011	69	0.06963	-0.02032		0.19986	0.12139	0.20025	0.01810
168	C-C-P-M-L	1.994	59	0.07024	-0.01991		0.19978	0.12216	0.19982	0.01062
	M-Q-C	1.988	29	0.07036	-0.02005		0.20005	0.12199	0.20149	0.01179
		ESTIMATION VALU	JES OF PAR	TABLE V AMETERS AND N	VII ⁄ISE of mati	RICES F	OR THE SIXTH	CASE		
n	Matrix	B0		61	62		63	θ	λ	MSE
56	C-C-P-M-L	0.484	14	0.30038	0.19983		0.40027	0.11638	0.20080	0.03047
	М-О-С	0.481	35	0.30041	0.20004		0.40034	0.11522	0.20351	0.03342
112	C-C-P-M-L	0.509	28	0.29939	0.20020		0.40007	0.12116	0.20014	0.01463
	M-Q-C	0.485	01	0.30048	0.19989		0.40016	0.12079	0.20064	0.01505
168	C-C-P-M-L	0.487	25	0.30040	0.20007		0.40009	0.12122	0.20017	0.01038
	M-Q-C	0.501	16	0.29992	0.20000		0.39989	0.12191	0.19993	0.01061
		ESTIMATION VALUE	ES OF PARA	TABLE V METERS AND MS	/III SE of matri	CES FOI	R THE SEVENT	'H CASE		
n	Matrix	B0	<u>61</u>	62		ß3	A		λ	MSE
56	C-C-P-M-L	0.11476	0.09850	0 1001	4 0	10036	0.46	630	0.80077	0.13060
20	M-O-C	0.05070	0.10082	0.1007	9 0.0	09999	0.46	726	0.80164	0.15005
112	C-C-P-M-L	0.10801	0.09895	0.1003	9 0.	10058	0.48	237	0.80047	0.06430
	M-Q-C	0.06484	0.10094	0.1001	4 0.	10019	0.48	334	0.79963	0.06839
168	C-C-P-M-L	0.08800	0.10036	0.0997	3 0.	10021	0.49	019	0.79962	0.04180
	M-Q-C	0.10254	0.09966	0.0996	8 0.	10030	0.48	880	0.80114	0.04413
		ESTIMATION VALU	JES OF PAR	TABLE : AMETERS AND N	IX ⁄ISE of mati	RICES F	OR THE FIFTH	CASE		
n	Matrix	<u>60</u>		61	62		ß3	θ	λ	MSE
56	C-C-P-M-L	2.0395	8	0.06750	-0.02037		0.20072	0.47238	0.80153	0.13667
	M-Q-C	2.0232	2	0.06855	-0.02068		0.20000	0.46885	0.79856	0.14178
112	C-C-P-M-L	2.0382	7	0.06822	-0.01992		0.19960	0.48476	0.79857	0.06272
	M-Q-C	1.9679	6	0.07029	-0.01944		0.20073	0.48648	0.79932	0.07059
168	C-C-P-M-L	1.9500	4	0.07169	-0.01990		0.19978	0.49172	0.79976	0.04114
	M-Q-C	2.0100	1	0.06961	-0.02003		0.19950	0.49104	0.80075	0.04478
		ESTIMATION VALU	JES OF PAR	TABLE AMETERS AND N	X ISE of mate	RICES FO	OR THE NINTH	I CASE		
n	Matrix	80	<b>R1</b>	R7		ß3	A	1	λ	MSE
56	C-C-P-M-L	0.43081	0.30189	0 1999	5 0.4	40043	0 47	015	0.79623	0.13330
50	M-O-C	0.50463	0.29903	0.2006	7 0	39960	0.46	771	0.79498	0.13771
112	C-C-P-M-L	0.49181	0.30027	0.1995	9 0.	39963	0.48	266	0.79872	0.06278
	M-Q-C	0.47587	0.30063	0.1995	1 0.4	40015	0.48	305	0.80057	0.07026
168	C-C-P-M-L	0.50086	0.29975	0.1999	5 0	39994	0.48	919	0.80098	0.04018
	M-Q-C	0.49312	0.30009	0.2002	3 0.	39977	0.48	725	0.79963	0.04487

	LETIMATION VALUES OF TARAMETERS AND NISE OF MATRICES FOR THE TENTH CASE									
n	Matrix	β0	β1	β2	β3	$\theta$	λ	MSE		
56	C-C-P-M-L	0.09174	0.09990	0.10049	0.10015	0.11521	0.79954	0.03522		
	M-Q-C	0.10529	0.09985	0.09943	0.10022	0.11646	0.79984	0.03535		
112	C-C-P-M-L	0.09534	0.10001	0.10009	0.10014	0.12016	0.79980	0.01647		
	M-Q-C	0.10867	0.09961	0.09991	0.10011	0.11950	0.79886	0.01890		
168	C-C-P-M-L	0.09777	0.10022	0.10009	0.10044	0.12182	0.79912	0.01159		
	M-Q-C	0.09322	0.10012	0.10005	0.10013	0.12198	0.80013	0.01177		
			ТАІ	RI F XII						
	Est	IMATION VALUES OF	PARAMETERS AN	D MSE OF MATRIC	ES FOR THE ELEV	ENTH CASE				
n	Matrix	β0	β1	β2	β3	θ	λ	MSE		
56	C-C-P-M-L	2.00991	0.06959	-0.02019	0.19990	0.11573	0.79825	0.03380		
	M-Q-C	1.97368	0.07064	-0.01981	0.20035	0.11656	0.79931	0.03612		
112	C-C-P-M-L	1.99964	0.07007	-0.02020	0.19979	0.12143	0.80027	0.01607		
	M-Q-C	1.99641	0.07001	-0.01989	0.20007	0.12039	0.79807	0.01768		
168	C-C-P-M-L	1.99669	0.06999	-0.01992	0.20018	0.12232	0.80039	0.01105		
	M-Q-C	1.99708	0.07003	-0.01987	0.19984	0.12288	0.79999	0.01154		
			ТАБ	R F XIII						
	E	STIMATION VALUES	OF PARAMETERS	AND MSE OF MATE	LCES FOR THE FIF	TH CASE				
n	Matrix	β0	βI	β2	β3	θ	λ	MSE		
56	C-C-P-M-L	0.50365	0.29962	0.20000	0.39990	0.11610	0.79879	0.03005		
	M-Q-C	0.52298	0.29888	0.19968	0.40036	0.11531	0.79842	0.03459		
112	C-C-P-M-L	0.51507	0.29928	0.19994	0.40026	0.12111	0.80022	0.01476		
	M-Q-C	0.50282	0.29993	0.20002	0.39988	0.12176	0.79940	0.01548		
168	C-C-P-M-L	0.49362	0.30027	0.20004	0.39972	0.12188	0.79924	0.01006		
	M-Q-C	0.49073	0.30036	0.19988	0.40001	0.12211	0.79981	0.01029		

TABLE XI Estimation values of parameters and MSE of matrices for the tenth case

From the Tables, we conclude that the best matrix for estimating the spatial negative binomial regression model is the proposed modified longitude matrix, and therefore we will rely on it in the applied aspect.

#### B. Good Matching of Data

The relationship between climate and transportation is ancient and close since the beginning of the process of trade exchange on a large scale between human societies. The climate was a contributing factor to this trade exchange, especially in the period when humans used sailing ships in human transportation and trade. We will study land transport, as it is also affected by climatic events, and to a lesser extent. Weather events may uproot railways, as can heavy rains, and disruption of traffic and traffic signals as a result of fog or as a result of freezing, although they have a significant impact on traffic safety.

In order to ensure that the data of the dependent variable (the number of traffic accidents) is subject to a negative binomial distribution, goodness-of-fit tests provided by the ready-made statistical program Easy Fit 5.6 were used. These tests are the Kolmogorov-Smirnov (KS) Kolmogorov-Smirnov test and the Anderson-Darling (AD) test. These tests test the following hypothesis:

- H\_0: y~Negative Binomial
- H\_1: y≁Negative Binomial

It is clear from Table 6 that the probability value of the Kolmokrov-Smirnov (KS) test is (0.17823) greater than the significance level (0.05), which indicates acceptance of the null hypothesis that the data follows a negative binomial distribution, and this is supported by the Anderson-Darlink (AD) test. The probability value of this test is equal to (2.5018), which is greater than the significance level (0.05). The results of the two tests were as in Table 14.

TABLE XIV GOODNESS-OF-FIT TESTS FOR THE VARIABLE NUMBER OF TRAFFIC ACCIDENTS

	KS	AD
P- Value	0.17823	2.5018

## C. Moran's spatial dependence test

The results of Moran's test for the spatial dependence of the proposed length matrix were obtained, and the results are as shown in Table 15:

	TABLE XV						
	MORAN TEST RESULTS						
Moran I	Expected	Variance	Z-Statistic	P-Value			
0.18	-0.018	0.0005	9.02	< 0.0001			

The results indicate that there is spatial dependence based on the P-Value, which is less than the significance level of 0.05.

#### D. Model estimation

The maximum likelihood method was used to estimate the parameters of the spatial binomial regression model based on the proposed longitudinal weight matrix because it gave very satisfactory results according to the simulation results as shown in Table 16

TABLE XVI Parameter estimates							
Parameters $\beta_0$ $\beta_1$ $\beta_2$ $\beta_3$ $\theta$ $\Lambda$							
Estimates	-1.89131	0.09610	0.01544	-0.00148	2.60530	0.87472	

Based on the results on the Figure 1, the observations of the dependent variable were estimated, and the following Figure shows a graph of the estimated values with the actual values of the number of traffic accidents in Iraq for the year 2022.



Fig. 1 Currently, estimated values of the dependent variable

#### IV. CONCLUSION

The spatial negative binomial regression model proved its efficiency in light of the two adjacent matrices adopted in the research with large sample sizes. This is evident from the decrease in the mean square error values, at a sample size of 168, where the weight matrix for the modified longitudes showed its efficiency when estimating the spatial negative binomial regression model. This is due to the low values of the mean square error (MSE). In the applied side and based on the results of Moran's coefficient, it was concluded that the count data represented by the number of traffic accidents in the Iraqi governorates suffers from spatial dependency, and notice the correlation of the dependent variable. The number of traffic accidents has a positive, significant relationship with the two explanatory variables: the general average temperature and the average rainfall. That is, as temperatures increase, traffic accidents increase with them. The greater the amount of rain falling, the greater the number of traffic accidents depending on the type of road, the third explanatory variable, the amount of falling dust, is inversely related to the number of traffic accidents. We recommend Using a spatial negative binomial regression model in the economic and health fields

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