

Modern Monitoring Instrument to Support Fishing Vessel Operation and Maintenance: A Review

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Abstract— Determining the maintenance strategy for fishing vessels propulsion engines can use engine operational monitoring data. This data is used to prepare the implementation time, spare parts, labor, and costs. Unfortunately, many fishing vessels do not have this data. Currently, electronic devices are available for monitoring machine operations. This device is cheap, easy to use, takes responsibility for various physical quantity parameters, displays it on LCD, stores it digitally, and transmits data wirelessly. This paper aims to review the application of engine operational monitoring tools to apply to fishing vessel propulsion engines. The material used is scientific articles consisting of journals and proceedings indexed by online databases. Several keywords are used to obtain scientific articles that are suitable for the study. The method used is a literature review that is systematically reviewed by applying inclusion and exclusion. The results obtained in this article are the parameters for monitoring propulsion engines, namely temperature, pressure, rotational speed, and hours the engine runs. The monitoring device requires sensors to detect physical parameters, a microcontroller to process data, an LCD to display monitoring results, and memory to store data to obtain this data. The device supports wireless communication via Bluetooth or WiFi radio signal. Fishing vessels are operating in offshore areas that are not covered by internet networks as IoT communication transmissions. Further research on how to transmit operational engine data from offshore to onshore without an internet signal so that data can be accessed using the internet network.

Keywords— Monitoring devices; maintenance tools; propulsion engines; fishing vessels.

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I. INTRODUCTION

Fishery activities in the north sea of Java Island are dominated by capture fisheries, which is 10.31% of the total number of fishermen all over Indonesia [1]. Those fishery activities use various fishing vessels, ranging from a fishing vessel without an engine to a fishing vessel equipped with an engine. Capture fisheries in Indonesia are dominated by traditional fishermen who use wooden fishing vessels [2], [3]. The fishing vessel can operate in a fishing ground that is relatively far from the home base. Generally, the time required for fishing vessels with a weight of 10-30GT to catch fish can reach up to 6-20 days [4], [5], while fishing vessels with purse seine fishing gear weighing up to 120GT can sail for up to 60 days [6].

Nevertheless, the machinery conditions of those traditional fishing vessels are relatively complex. It starts from the propulsion engines to the engine crew as an engine operator. An engine crew of a fishing vessel as an engine operator must have competence in fishing vessel machinery proofed by the

possession of an ATKAPIN seafarer expertise certificate. However, in actual conditions, many engine crews do not have this certificate. Skills as an engine operator are limited to operate and simple maintenance and obtained through experience. This condition causes engines lifetime is not as expected.

Most of the engines that they use as vessel propulsion are not for marine usage. However, they use modified used truck engines. It caused the price of a truck engine is considered cheaper than a marine engine. Moreover, spare parts are available. The worse condition is some engines whose control instruments do not work and do not repair yet, so they cannot be used. Some of these controls include controls for engine coolant water temperature, lubricant temperature, hour meter, and others control.

When the engine is running, one of the engines watchkeeping activities is journaling the engine condition. Such as engine rotational speed, working temperature, pressure, and engine operating hours. However, under the nonfunctional instrument condition, engine running condition parameters cannot journal correctly. Parameter recording is

only based on estimation by noticing to audio-visual and vibration. The temperature value of engine cooling water and lubricant is obtained by sensing the cooler surface with a hand. Those journaling activities are inaccurate and difficult to use as a guide for monitoring engine conditions for maintenance and repair actions.

In the absence of correct engine data conditions, the preference maintenance action is corrective maintenance (CM). Moreover, if all engine components were maintained, it would be expensive [7]. CM is only better for the low-risk parts.

Generally, ship owners implement two maintenance strategies to get optimal engine conditions. The first is corrective maintenance. This maintenance strategy can be called repair maintenance and chosen when the engine is failing to operate [8]. The second is preventive maintenance and is divided into two, namely time-based maintenance (TBM) and condition-based maintenance (CBM) [9], [10]. TBM is carried out regularly, planned at intervals of maintenance conducted before. CBM is an engine maintenance approach that emphasizes the combination of reliability models based on engine performance data collected from the engine operating conditions. CBM is also a maintenance action that utilizes real-time data and information on engine operating conditions and provides recommendations for maintenance actions based on these conditions [11]. It aims to minimize unnecessary maintenance actions as the engine is still in a decent operating condition and prevents failure on the applied preventive maintenance components due to the earlier failure time.

CBM is a part of preventive maintenance, which is also called predictive maintenance. It has been widely used by industries in various disciplines such as electricity, manufacturing, shipping, nuclear, and others. CBM is a modern maintenance strategy and a popular maintenance technique [12]–[15]. The principle of CBM action is to minimize engine maintenance costs by avoiding maintenance actions on components that are still run properly to increase engine availability [16], [17].

Components that are decent for operation and almost failure will show signs, symptoms, and indications indicated by the engine operating condition parameters [18], [19]. This engine condition parameter is obtained by inspecting or monitoring the engine [20], [21]. One of the successful implementations of the CBM strategy depends on a satisfactory inspection or monitoring system and produces accurate operational condition data of the engine.

Recently, many engines have used sensors and microcontrollers for inspection/monitoring and collecting data to implement CBM strategies. Awang [22] applied CBM to a two-stroke vessel propulsion engine using ultrasound signals. His paper stated that ultrasound signals could be applied to identify excess friction earlier. Meanwhile, Murty [23] uses vibration and temperature sensors for monitoring compressor health. The sensor senses abnormalities in misalignment, non-linearity, vibration, and temperature in the compressor which are recorded in real-time. Angius [24] for the CBM program using several sensors connected in the network to collect health condition data on critical components.

This paper describes the application of an open-source microcontroller and sensor device for recording and monitoring a real-time engine operational condition used as data on CBM action of fishing vessel engines. The device was chosen because relatively low-cost, an open-source service that makes it easy to modify and is relatively accurate and reliable.

II. MATERIALS AND METHOD

This article was compiled using the literature review method from several scientific articles about monitoring devices that use open source to monitor engine operations in real-time. The stages of the research method are carried out following Fig. 1.

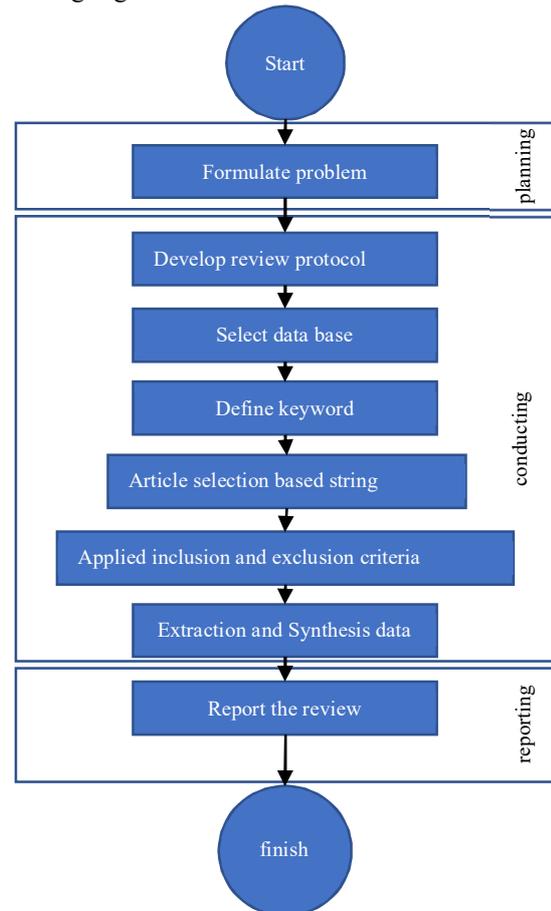


Fig. 1 Research method flow chart [25]

In this study, literature review carried out in several stages as follows Fig. 1: section A. preparation which includes 1) determining the topic of the problem to be discussed with several questions, 2) making questions; section B. conducting a review which includes 1) determining the protocol to be used, 2) selecting a digital database, selected based string keyword article, 3) selecting articles by applying inclusion and exclusion, 4) data extraction; and section C. report the results of the review.

A. Planning

Determining the topic: In the preparation stage, the thing to do was to choose the problem to be studied i.e., the operational monitoring equipment for the vessel engine propulsion. Determining questions: questions were conducted

to retrieve, identify, and select scientific articles discussing modern devices used to monitor engine operations. The questions were divided into two groups, as shown in Table 1 i.e general questions (GQ) and specific questions (SQ). GQ aims to help develop research, and SQ aims to identify engine monitoring tools to support CBM.

TABLE I
RESEARCH QUESTION

RQ	Question
General question	
GQ	How engine monitoring supports CBM
Specific question	
SQ1	What ability is needed to obtain operational data for fishing vessel propulsion engines?
SQ2	What parts can be used as a monitoring device for fishing vessel propulsion engines?
SQ3	How is the implementation of monitoring equipment for propulsion engines on fishing vessels?

B. Conducting

Developing a protocol: in carrying out research using a predetermined protocol so that research does not widen and become biased. Protocols used to formulate questions, strategies used to search for data, selection with inclusion and exclusion criteria, data synthesis. The stage of conducting the review in Fig. 1. The first step was articles search in the Google Scholar online database using the following keywords and strings.

“(device OR tools) AND (monitoring OR recording) AND (operational OR maintenance) AND (machinery).”

Articles obtained from search results were read in the title, abstract, introduction, and conclusion sections. To use articles properly, inclusion criteria were applied to determine the articles to be used. The inclusion criteria used were 1) articles can be in the form of journals or proceedings; 2) the articles were written in English, and some articles can be in Indonesian (the object of fishing vessels in Indonesia); 3) Articles written in 2017-2021; 4) Studies that discuss the concept of engine monitoring parameter using micro-controllers; 5) Studies that discuss and answer GQ and SQ (Table 1).

The next stage applied exclusion criteria to filter and eliminate irrelevant articles. The exclusion criteria used were 1) Studies that do not discuss the concept of engine operational monitoring parameters using micro-controllers, 2) Studies that do not discuss and answer GQ and SQ; 3) Book articles and dissertation or thesis reports; 4) Articles from searches that cannot be downloaded from the database.

After the exclusion stage, all selected articles were read and studied to find out which parts were discussed to answer the GQ and SQ questions.

C. Reporting

The report was made based on a general perspective to answer research questions that have been determined previously. The report was written by using Microsoft Office tools. The sentences that match the discussion were then quoted and entered as a library. Mendeley's citation manager was used to organize and filter to create well-organized

bibliographic references. This process was carried out by three people who know machine parameter monitoring and have a mechanical engineering background in different scientific fields.

III. RESULTS AND DISCUSSION

A. GQ (Engine Monitoring Supports CBM)

Engine monitoring onboard is a periodic engine inspection that aims to maintain the engine running in good condition so that the instrumentation can run properly. In the implementation, engine monitoring is conducted by the engine crew checking the engine's operational performance conditions and structured documenting in the engine logbook. The result recorded in the logbook is the value of the engine parameters in real-time at any given time interval [26]. When the engine runs in an abnormal condition, that condition is also recorded in the engine logbook.

The criteria for monitoring devices that can be used to support the implementation of CBM, i.e., can collect data on engine parameter values, classify data, and detect disturbances that occur in engines. In 4.0, temperature monitoring allows monitoring in real-time [27], [28]. The monitoring results can be saved or recorded in digital data form, i.e., log data used for various purposes. One of them is for CBM action analysis.

Obtaining engine operational log data as an analysis material for implementing the CBM strategy involves the sensor device designated to inspect the engine [29]. Inspecting engine operating parameters routinely by humans requires a considerable cost. Therefore to reduce the cost, electronic sensors can be used [30]. Engine monitoring devices with electronic sensors can be applied because they have a small dimension size, vibration resistance, no moving parts, lower prices, and ease to get [31], [32].

Generally, fishing vessels use diesel engines as their propulsion. Diesel engines are chosen because of their high efficiency, power, and reliability compared to other compatible power sources [33]. To keep the diesel engine in good condition, it is necessary to monitor the operating conditions of the machine parameters. These parameters are lubricant temperature and lubricant pressure [34], engine coolant temperature [35], rotational speed [36], and battery charger voltage [37]. The other essential data is the engine running hours (RH), where RH functions to find out the accumulative time of how long the engine has been running. With this condition monitoring data, maintenance decisions can be made as needed. Besides that, which is no less crucial, maintenance can be conducted effectively and efficiently and contribute to the business profitability [38].

B. QSI (The abilities needed to obtain operational data of fishing vessel propulsion engines)

Various existing monitoring devices, although of different types and technologies, still use the same principles. In principle, the monitoring device consists of three stages, i.e., sensing, processing, and reporting [39] Fig. 2. The required criteria ability as a monitoring device on fishing vessels are shown in Table 2.



Fig. 2 Monitoring Principle [39]

TABLE II
MONITORING DEVICE ABILITY

Required Function	Detail
Reading engine running parameters	Convert mechanical data such as temperature, pressure, voltage, engine speed, operational time, and running hours on vessel propulsion engines into analog data.
Processing digital data	Process digital data to produce output that can drive the actuator, save it in memory and show it on display.
Saving data	Collect and save data from engine operational data processing held in memory on parameters measured by time in real-time.
Reporting data	Report the results of parameter monitoring through the display so that the engine operator can understand it.
Sending data	Processed data (collected, grouped) can be sent to other devices for analysis purposes. It can conduct using a cable or wireless.

C. QS2. (The parts used as a monitoring device for fishing vessel propulsion engines)

The engine monitoring device generally consists of several parts Fig. 3. At the stage of sensing the parameters of a physical phenomenon in the engine is the sensor duty [40], [41]. This monitoring device requires several sensors to detect some physical changes. Some of the physical data obtained by the sensor are raw data that must be processed and analyzed further by the processor, i.e., a microcontroller [42], [43]. However, to display data processed by the processor using the LCD display [44], while Ruobing [45] used the display on a computer or smartphone. Reporting using this device can make it easier for users, i.e., vessel engine operators, maintenance technicians, and vessel owners.

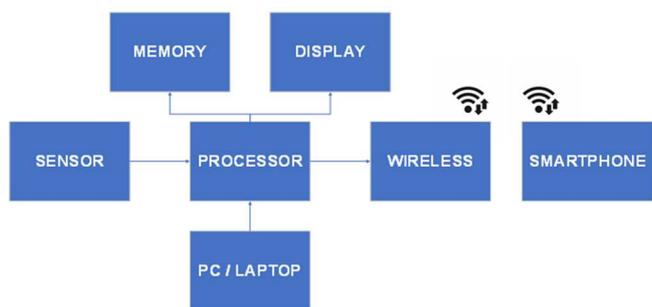


Fig. 3 General Design of Engine Monitoring Device That Uses A Wireless Connection [46]

This device is programmed to receive various input signals from several sensors placed at several points, then read engine parameters, process, and display. The results of the data processor can be used directly by the control system.

Moreover, it also utilizes as a trigger for engine control actuators such as relays, solenoids, and alarm warning signs.

Through a display embedded in this device, engine operators would know engine performance easier. Start from the cooling water temperature, lubricant temperature, lubricant pressure, battery voltage conditions, and how long the engine has been running. It can also help operators take the right steps in carrying out operations and engine maintenance well.

The processed data by the processor is saved temporarily by the device. However, to save lots of data for a longer time, the data is saved periodically in the embedded memory [47]. Embedding a memory to the device can help technicians or the maintenance team to read operational history and engine failure when the vessel engine is running. This data is useable as a material for making engine maintenance planning decisions.

A monitoring device can use an open-source processor to process data in the physical magnitude form and report it through the monitor. When the device detects abnormal conditions on the engine, this device can give a warning signal [48] so that the operator or vessel crew can provide corrective action.

1) *Sensor*: Vessel propulsion engine running performance is affected by several physical parameters, including engine coolant temperature, lubricant temperature, lubricant pressure, engine rotational speed, and engine running hour meter. It causes monitoring devices requiring multiple detection sensors [49]. The essential things in diesel engine operation, such as engine cooling, lubricant pressure, structural deficiencies, and breakdown of the indicator, can be monitored using sensors [50]. Some of the sensors used to detect the engine's physical parameters are shown in Table 3 [51]–[54]. The references that discussed the sensor to determine the physics parameter are shown in Table 4.

TABLE III
REQUIRED SENSOR TO DETECT ENGINE RUNNING

Physical Parameters	Part which Monitored
Temperature	Cooling water temperature at the inlet and outlet of the heat exchanger and the lubricant in the oil reservoir
Pressure	Lubricant circulation pressure in the engine lubrication system
Engine speed	Engine rotational speed
Running hour	Length of engine running time

A diesel engine is an internal combustion engine, which converts chemical energy obtained from liquid fuel and burns it in the combustion chamber to become heat energy [55]. The heat energy is used to push the piston from TDC to BDC to generate mechanical energy that transfers to the propeller to drive the vessel. Running a diesel engine will generate heat, where the maintained heat when the engine running is between 75 - 80°C [56], and excessive heat will cause the engine to deteriorate fatal damage. In diesel engines, the monitored temperatures are cooling water temperature and lubricant temperature [57]. Determine the cooling water temperature value, a temperature sensor put on the liner cylinder's water pipe [58], [59]. Meanwhile, to find out the lubricant temperature value, a sensor was placed on the engine crankcase as a lubricant reservoir for the engine.

TABLE IV
PARAMETERS FOR MACHINE MONITORING

Reference	On The Display	The Used Data for Monitoring
[57]	Lubrication System Temperature	Pressure and temperature lubrication to detect a disturbance
[58]	Water Temperature	Engine diesel coolant temperature
[59]	Cylinder Liner Temperature	Energy efficiency
[60]	Fuel Temperature	Remote monitoring thermal preparation process an engine
[61]	Vehicle Temperature	Engine temperature when vehicle running
[63]	Oil Pressure	Pipe leakage detection
[64]	Hydrogen Pressure	Hydrogen flow control in the simple furnace
[65]	Engine Rotational Speed	Rotational speed to performance and emission comparison
[66]	Engine Rotational Speed	Rotational speed to performance and emission comparison
[67]	Rotational Speed	Rotational speed to measure wind power
[68]	Rotational Speed	Rotational speed of diesel engine with alternative fuel
[69]	Running Hour	Running hour to analysis reliability
[70]	Running Hour	Engine conditions related to the component lifetime
[71]	Running Hour	Determine the wear of rotating engines by monitoring running hours

Manufacturers produce several sensors to measure temperature, i.e., LM35, DHT11, DHT22, and DS18B20. Gritsuk [60] used a DS18B20 thermocouple sensor to measure temperature coolant in the diesel engine. DS18b20 is a relatively accurate temperature sensor with an accuracy of 9 to 12 bits, in a temperature range of -55°C to 125°C [61]. This sensor communicates to the microprocessor using 1 data cable and one ground cable, where the required voltage source is obtained from the data cable. This sensor can work 64bit to connect one communication cable with several different functions [62].

When a diesel engine is running, many component mechanisms are connected and rubbed each other. If the component that rubs each other did not well lubricated, it would impact wear. Many diesel engines currently apply a pressure lubrication system, where the gear pump sucks lubricant from the crankcase and discharges it into the gaps of friction objects. Monitoring lubricant pressure in diesel engines is significant because it determines the condition of the lubricant circulation. Knowing the lubricant condition in real-time makes it possible to prioritize the correct maintenance schedule accurately.

A good lubricant circulation of a diesel engine is indicated by lubricant pressure value following that determined by the manufacturer. In contrast, lubricants with pressures below manufacturer standards show a disturbance in the lubricant circulation. The trouble of lubricant circulation must be immediately taken into action to prevent further damage such as jamming the piston on the cylinder liner, wearing valve, bearing, and the shaft on the engine.

Several sensors can be used to measure pressure. Okpare [63] used the HK1100c sensor to monitor leaks of pipelines that carry oil. Darjat [64] also used HK1100c to take control

of hydrogen and oxygen pressure in his paper. The HK1100c pressure sensor can read pressure ranging from 0-1.2 MPa with an accuracy of $\pm 1.0\%$ FSO. This sensor works using a 5V DC voltage. The diesel engine used in fishing vessels is a high-speed diesel engine. Stationary rotational speed reaches 800 rpm, and when the vessel sails, it can reach 1200 rpm. Engine speed is essential to monitor because the number of engine revolutions considerably influences a diesel engine's performance. The number of engine revolutions will affect engine performance [65], while engine performance is affected by water temperature and lubricant temperature [66].

To monitor the amount of engine rotational speed using a rotation sensor. Some sensor devices that can detect engine rotational speed include IR sensors with the optocoupler or proximity principle and inductive sensors with the proximity principle [67]. Gabina [68] measured rotational speed in a diesel engine using an inductive proximity sensor. This device can provide contactless measure rotational speed by utilizing the eddy current field principle.

Occurrence time is always included in monitoring to know the occurrence time accurately. It can help determine the timing of occurrence and calculate how long the engine has been running [69]. To determine the occurrence time and how long the engine has been running, a running hour (RH) meter can be used. RH meter works by recording every running hour, and the value will continue to increase over time. If the engine did not run, RH would stop recording the running time. RH is beneficial for knowing engine conditions related to the component lifetime, which is essential in calculating the reliability value [70]. RH can also help analyze engine failures, such as Poppe [71], in his research to determine the wear of rotating machines by monitoring running hours.

The device in charge of keeping track of time is a "real-time clock" commonly known as the RTC. RTC is an electronic clock that calculates the time from seconds to years and saves it in digital data on an added memory device [72]. RTC is used by Iskandar [73] as a timer for data collection in a photovoltaic photosystem application. A list of sensors that can be used as a monitoring device for vessel propulsion engines is shown in Table 5.

TABLE V
LIST OF THE SENSOR TO MONITOR DIESEL ENGINE

Type of sensor	Magnitude Detected	Advantages	Disadvantages	Application Usage
thermal	temperature	Stable, good accuracy, wide measuring range.	It is challenging to detect fast and random changes	Detecting the temperature of the coolant and engine oil
Inductive electromag netic	pressure	Compact, fast response, good sensitivity.	Sensitive to magnetic fields and temperature	Oil pressure, gas pressure
Inductive proximity	Engine rotational speed	Compact, fast response, good sensitivity, and applicable.	Sensitive to magnetic fields and requires a short distance for good accuracy.	Measuring engine rotational speed
Oscillator	Time	Accurate, compact form, uses low power.	Sensitive to temperature.	Measuring time in real-time

2) *Processor*: The data obtained by the sensor to detect physical quantities cannot be read directly by humans, the process still requires a processor. Several processors can be used to process data, including Arduino, Raspberry Pi, Intel Edison, Mediatek Linkit One, NVIDIA Jetson Nano [74]. Arduino and Raspberry Pi are the most widely used processors because of their simplicity and easy operation [26], [75] show in Table 6. Arduino is a processor that uses an open-source platform so that the hardware or software can be modified as needed to make it easier to use [76]. Temperature sensors with code DS18B20 can use Arduino as the processor [77], [78]. Likewise, in his article Zariatn [79] measured water pressure using the HK1100c sensor with an Arduino - board processor for measuring pressure. Similarly, to get the rotational speed and time of Arduino, Putu [80] used Arduino as the processor. The Arduino board is hardware, where to run commands requires commands using the C ++ language. Creating commands, modifying and uploading commands in C ++ using the open-source Arduino IDE software [81].

TABLE VI
ARDUINO PROCESSOR DIFFERENCES WITH RASPBERRY PI

Criteria	Arduino	Raspberry Pi
General Processor	Microcontroller AVR 8-bit, simple, applicable, ATmega328P @ 16 MHz	Microcomputer ARM 64-bit, complex, BCM2837 @ 1.2 GHz
Program running (multitasking)	At the same time, only one program can be run.	At the same time, several programs can be run.
Connectivity	There is no built-in wired or wireless module but can add an add-on module to provide that capability.	It has built-in WiFi, Bluetooth, and ethernet connectivity.
Operating system	None	Raspbian
Memory	Arduino is equipped with three types of memory, namely flash, SRAM, and EEPROM.	It is equipped with RAM memory capacity of 1 GB (Raspberry Pi 3 2B / 3B / 3B +)
Port	A single USB port is provided for program uploading and an ICSP header for debugging.	It has a USB host port, HDMI, CSI, DSI, audio jack, and an ethernet port.
Programing Language	C dan C++	Phyton, C, C++, ruby

3) *Display*: To report data that the processor has processed can use the display. Several displays have been used for monitoring devices, i.e., LCDs, smartphones, and computers. The LCD is an electronic display that uses liquid to display visual information. A compact form makes it easy to attach to monitoring devices and easy to use with Arduino [75]. Several sizes of LCDs that are widely used to display monitoring results are 16x2 and 16x4. The development of electronics is rapid, and it is also applied to smartphones and computers. Smartphone devices are also similar to computers, having a processor, memory, and display. Smartphones can also display the results of monitoring carried out by sensors and processors [82], [83]. The advantages of smartphone

monitoring can be conducted via mobile as long as it is connected to a network of engine monitoring devices.

4) *Communication*: The engine monitoring device can monitor the engine's operating conditions directly at the engine location, where the sensor is permanently installed on the monitored part. The results of this monitoring are displayed visually through the display. Communication between devices and engine operators can be done in several ways, i.e. conventional, portable, Wireless communication in the local area, and internet communication.

The conventional diesel engine operational monitoring device on fishing vessels is the engine manufacturer's default and permanently installed on the dashboard. This conventional device is still simple and relatively more expensive, as the communication between the sensor and the dashboard uses cables and capillary pipes, so the engine operator must record the engine's operational monitoring.

The portable type of monitoring device is compact, lightweight, and can be used on mobile. This type is widely used to monitor engine operational parameters and occurrences when the engine is running. Some authors of scientific articles, such as Krishnamoorthi [84] used portable monitoring devices to analyze diesel engines' availability, performance, and emissions. This type of device has a weakness, i.e., the sensor placement is not fixed. It can cause noise in the measurement and causing measurement errors [85].

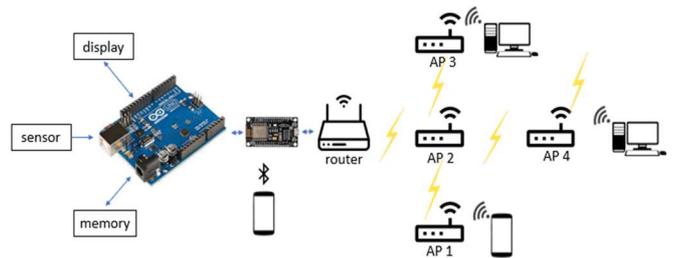


Fig. 4 Wireless engine monitoring can be accessed in a limited local area [26].

Wireless communication monitoring devices can be carried out in local areas without using the internet Fig. 4. The monitoring device with the wireless method works by collecting data. The data is processed by the processor and send to the operator's data [39]. Communication between devices and humans as technicians is wirelessly carried out by devices via Bluetooth [86]. Bluetooth exchanges information between Arduino equipment, smartphones, computers, and other devices that support Bluetooth transmission via free license short-range radio frequency communication channels [87], [88]. Other wireless communications can also use WiFi signals [89] to transmit radio signals at a frequency of 2.4GHz or 5GHz [90].

Modern monitoring devices currently widely used data communication using the internet based on micro-control [91] Fig. 5. Monitoring engine conditions using internet communication is used because it is practical. It does not need to be where the engine is located to monitor engine parameters but can be done in any area as long as the internet network covers the area. Monitoring devices with internet line communication are also used to monitor air pollution [92],

[93]. Using the internet line requires an MCU node module device to transmit data from the microprocessor to the internet network [94]. Through the internet network, engine monitoring results in real-time can be distributed and accessed in all areas covered by the internet network

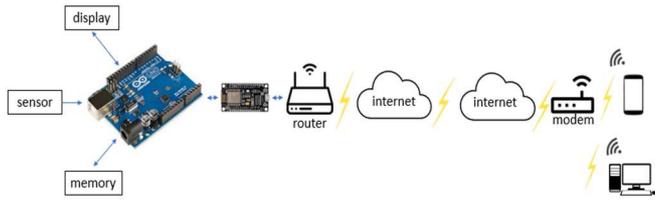


Fig. 5 Engine monitoring that can be accessed in the broader area using an internet connection [27], [95]

5) *Memory*: The success of condition-based maintenance measures on diesel engines is considerably influenced by data availability regarding engine parameters. To get engine parameter data in conventional monitoring, the operator must watch the engine panel and record it in the engine logbook. In modern monitoring devices, the data collected by the sensor is processed by a microprocessor, and then the data is collected and recorded on a memory card in the device. Memory cards are essential for storing large amounts of data for a long time [96]–[98]. Engine monitoring devices use a Micro SD memory card to save data on a memory card [99].

D. QS3. (The implementation of monitoring equipment for propulsion engines on fishing vessels)

The installed monitoring devices will be easy to implement. It is because this device works using a DC source that comes from vessel batteries. However, batteries on vessels generally have a 12-24 VDC voltage, while the voltage used by this engine monitoring device uses a voltage of 9-5 VDC. It requires a DC step down to use for the battery [100]. The voltage needed for each module, i.e., sensors, processors, displays, and memory.

The required sensor must be placed in the right position; improper sensor placement will result in fatal parameter measurement errors. For reading the engine rotational speed value, the sensor must be put in a place that can reach the part of the rotating engine shaft. Generally, the part used to measure rotational speed is the flywheel [101]. The sensor was placed a little ahead of the thermostat to get the engine coolant temperature value [102], [103]. It is because the coolant used after cooling the engine exits through this channel. The lubricant pressure sensor is placed in the lubricant channel after the lubricant filter [35]. The pressure sensor's position will detect a pressure change if a disturbance in the pump or dirt clogs the filter.

This monitoring device sold in the market is knockdown, easily assembled, and connected using a connecting cable. In the application, if much movement on the line can cause the cable connection to become loose [104] and cause errors in the parameter monitoring process. Fishing vessel movement caused by waves and engine activity allows the connection to loosen. Therefore to prevent this, all connecting cables must be connected using terminals that are screwed tightly and the processor placed in a fixed place. The LCD display is placed near the engine, on the control panel, and on the dashboard on the bridge to make engine parameters through this device read easier.

LCDs are placed near the engine to make monitoring and record actions on the logbook easier. Meanwhile, to complete engine monitoring easier, the generated data is distributed via wireless transmission to the local area network using a network topology as in Fig. 4. The physical quantity that the microcontroller has processed is emitted by the Bluetooth or WiFi module ESP8266 to be distributed by the router and accessed locally [105]. The router can be placed in the engine control room. The signal emitted by the router is then distributed evenly by the access point (AP). AP is set in several different locations, so that engine monitoring data can be accessed at the desired location using a smartphone or computer without going down to the control room or bridge.

Recorded engine operations in the engine logbook are also digitally backed up on the memory card. The digital data recorded on the memory card will help the engineer monitor engine operations while sailing. When the vessel returns to the home base to unload the caught fish, the engineer can download the memory card's monitoring data using smartphones or laptops. Engine monitoring data in digital form is more simple to process, such as tabulation, data sorting making it easier to perform computation and machine analysis for condition-based machine maintenance actions [106]. Engine monitoring data can calculate failure rates or changes in engine dynamics in the actual system. If the value deviated from the given value, it could be used as a trigger for taking condition-based preventive treatment measures [107].

E. Challenges of Applying IoT in Monitoring Vessel Engines

The growth of fishing activities in Indonesia tends to increase, especially at the industrial level, with a fleet of more than 30 GT. Fishing vessels with a size of more than 30 GT have a fishing ground of more than 12 nautical miles [108]. Monitoring devices using an Arduino microprocessor can be communicated using the internet [93], [109]. However, to support communication with the internet, the internet network must cover the area.

In Indonesia, fishing vessels operating areas more than 12 nautical miles from the coastline are mostly not covered by internet networks. Therefore, the future challenges to this device can be applied to IoT, so it requires a device that can send and receive signals with a radius of more than 12 nautical miles.

Based on an article written by Jiang [110], the communication system developed for use in the oceans is the maritime satellite and radio system. For satellite communication, the operational costs charged to the customers are relatively high because of the high investment costs. As a result, the satellite system to support engine monitoring communication via the internet is not comparable. The maritime radio system is the most popular. It is because of its ability to work in a large area of water. Very high frequency (VHF) signals operate in the range 156–162.025 MHz with a total bandwidth of 6.025 MHz and channel spacing of 50 kHz and 25 kHz capable of supporting analog voice communications up to about 111 km. Multiple VHF channels are used to develop a VHF data link (VDL) to provide data communication for an automatic identification system (AIS) at a maximum speed of 9.6 kbps.

A modulator is needed to use a VHF signal to superimpose the information data signal with a carrier frequency signal to

work in the Arduino ecosystem [111]. With this modulator, it is expected that the information signal transmitted from vessels in the ocean can be received at VHF receivers on land and then transmitted on the internet network.

IV. CONCLUSION

Currently, technology development is developing rapidly, especially in the engineering sector. Unfortunately, many engines used on traditional fishing vessels in Indonesia still apply old technology, conventional and manual engine monitoring devices. Even many instruments to measure engine parameters do not work, so that the vessels do not have engine operational data.

Engine operational data is an essential part of an excellent successful operation and engine maintenance. It is now possible to collect engine operational data using modern equipment and is easy to obtain at an affordable price. The engine monitoring device model described in this paper is relatively attractive because it uses several open-source sensors and microprocessors, but it has not been applied to conventional engines as propulsion of fishing vessels.

With digital data in the engine real-time, this device can facilitate planning for maintenance of vessel propulsion engines, preparing spare part supplies, maintenance costs, labor, and providing time to carry out the work. With careful planning, it is expected that there will be no undone engine maintenance actions, so that engine performance maintains in good condition.

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